

Analysis of Simple Stochastic Resonance with Various Noise Levels

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Abstract—In this paper, we analyze two simple stochastic resonances with various noise levels. First, it is analyzed that SR in a double-well potential which is well-known as a typical bistable SR model. Second, we add a one dimension to the bistable SR model and increase two stable states to the model, namely, the system is extended to “four-stable state”. Using these SR models, we carry out computer simulations and analyze the state of SR when the intensity of the noise is changed.

I. INTRODUCTION

Stochastic resonance (SR) is a nonlinear phenomenon in which a responsiveness of a system is improved by adding suitable noise to certain nonlinear systems. Recently, SR has attracted a great deal of attention from a variety of researchers, including nonlinear circuits and systems, semiconductor devices and biology[1]–[5]. In this paper, we consider that SR is applied to a communication system which is one of engineering systems. In standard communication systems, the signal detection becomes difficult according to increase a noise level. We expect that it is possible to detect the signal, which is influenced significantly by noise, by applying SR to the communication systems. For robustly detecting the signal in the communication system using SR, a control of SR by noise is very important task. Therefore, we consider that it is necessary to investigate a relationship between SR and noise.

Based on the above research background, this paper focuses on an analysis of SR with various noise levels using simple SR model. First, we analyze SR in a double-well potential which is well-known as a typical bistable SR model. The bistable system has two stable states (+1 or −1). Thus, we can regard the two stable states as 1bit data in the communication systems. Next, we add a one dimension to the bistable SR model and increase two stable states to the model, namely, the system is extended to “four-stable state”. In this paper, we call the extended SR model “SR in a quadruple-well potential”. Here, four-stable states of the extended system are (−1, −1), (+1, −1), (−1, +1) and (+1, +1). Thus, we can regard the two stable states as 2bit data in the communication systems.

This paper describes an outline of SR in the quadruple-well

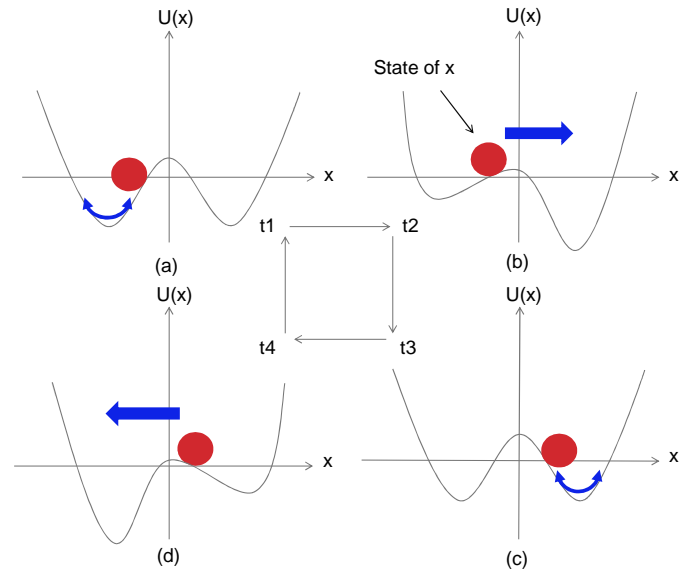


Fig. 1. Mechanism of SR in bistable system.

potential. In addition, we carry out computer simulations and analyze the state of SR when the intensity of the noise is changed.

II. SR IN DOUBLE-WELL POTENTIAL

Here, we briefly explain SR in the double-well potential. In Ref. [5], the bistable SR is performed by following equations

$$\frac{dx}{dt} = f(x) + Dn(t) + s(t) \quad (1)$$

$$s(t) = A \sin(2\pi f_0 t) \quad (2)$$

$$f(x) = -\frac{dU_0(x)}{dx} \quad (3)$$

$$U_0(x) = -\frac{1}{2}x^2 + \frac{1}{4}x^4 \quad (4)$$

Where $U_0(x)$ is a bistable potential having two local minimums, x is a state variable, $s(t)$ is an input signal, A is an

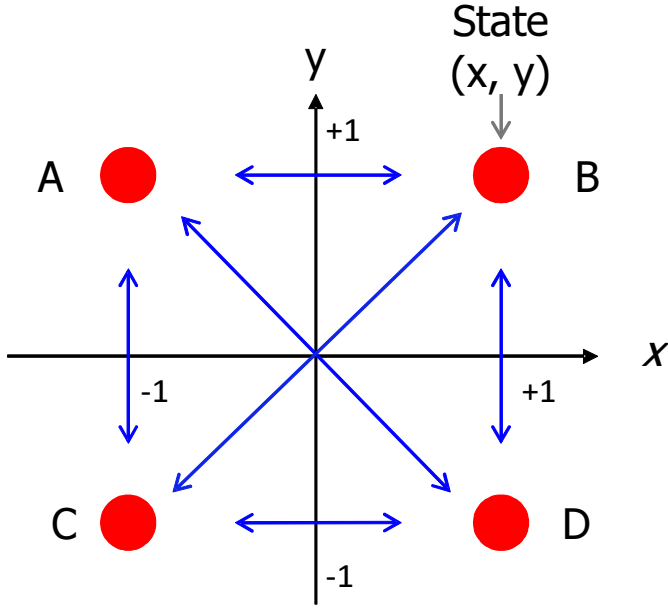


Fig. 2. Four-ideal-stable states.

amplitude of the input signal, n is assumed to be the additive white Gaussian noise AWGN, D is an intensity of noise. An effective potential $U(x, t)$ is described as follows.

$$\begin{aligned} U(x, t) &= U_0(x) + xs(t) \\ &= -\frac{1}{2}x^2 + \frac{1}{4}x^4 + xA \sin(2\pi f_0 t) \end{aligned} \quad (5)$$

Figure 1 shows a mechanism of SR in the bistable system.

III. SR IN QUADRUPLE-WELL POTENTIAL

In this study, we add a new state variable “ y ” to this bistable system and extend the system to SR in the quadruple-well potential. First, based on Eq. (1), the equation of the state x is described as follows.

$$\frac{dx}{dt} = f(x) + D_x n_x(t) + s(t) \quad (6)$$

Where n_x is noise added to the state x , D_x is an intensity of noise for the state x . Next, the equation of the new state y is described as follows.

$$\frac{dy}{dt} = f(y) + D_y n_y(t) + s(t) \quad (7)$$

$$f(y) = -\frac{dU_0(y)}{dy} \quad (8)$$

$$U_0(y) = -\frac{1}{2}y^2 + \frac{1}{4}y^4 \quad (9)$$

Where n_y is noise added to the state y , D_y is an intensity of noise for the state y . In this study, n_x and n_y are assumed to be (AWGN). Additionally, the values of n_x and n_y are different from each other. In other words, the n_x and n_y are independent of each other.

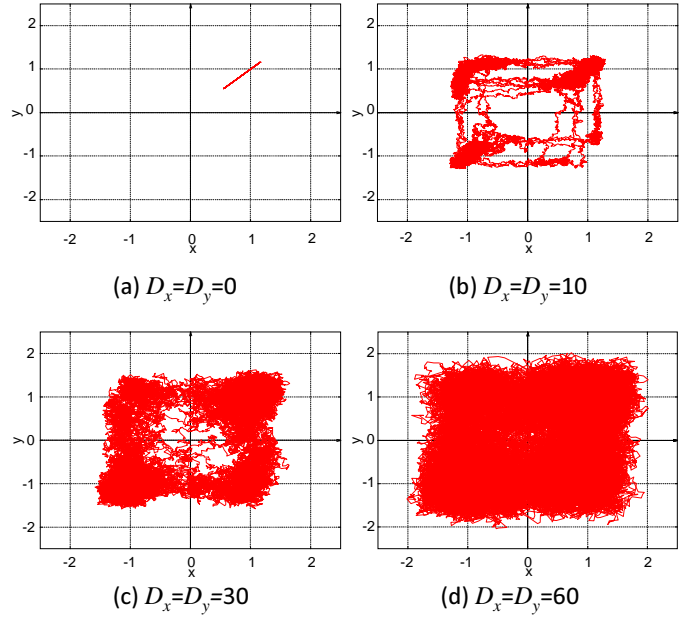


Fig. 3. Output of SR in four-stable state ($D_x = D_y$).

IV. SIMULATION RESULTS

A. Simulation conditions

Using the above system, we carry out computer simulations. In the simulation, the two states are expressed in (x, y) planes a coordinate (point (x, y)). Figure 2 shows four-ideal-stable states of SR in the quadruple-well potential in (x, y) plane. By changing D_x and D_y (i.e. noise level), we experiment to control four-stable states in this plane. As parameters of the simulation, the initial condition of x & y is “+1”, $t = 100,000$.

B. Results of same noise level ($D_x = D_y$).

Figure 3 shows simulation results for same noise level $D_x = D_y$. First, in the case of $D_x = D_y = 0$ (Fig. 3(a)), we can observed that the point (x, y) centers around $(+1, +1)$ since noise is not added to the system. Second, in the case of $D_x = D_y = 10$ (Fig. 3(b)), it can be confirmed that the point (x, y) moves the potential barrier and moves around the four-stable states. Third, in the case of $D_x = D_y = 30$ (Fig. 3(c)), the point (x, y) continually hops the potential barrier. However, we can see that the point (x, y) does not stay in one-stable state for a long time although the point (x, y) moves around the four-stable states. Finally, in the case of $D_x = D_y = 60$ (Fig. 3(d)), it can be observed that the point (x, y) move around (x, y) plane, regardless of the four-stable states.

C. Results of different noise level (fixed D_x , variable D_y).

Next, Fig. 4 shows simulation results for fixed $D_x = 10$ and variable D_y . First, in the case of $D_y = 0$ (Fig. 4(a)), the point (x, y) moves a little in y -axis. On the other hands, the point hops only in x -axis. Second, in the case of $D_y = 5$ (Fig. 4(b)),

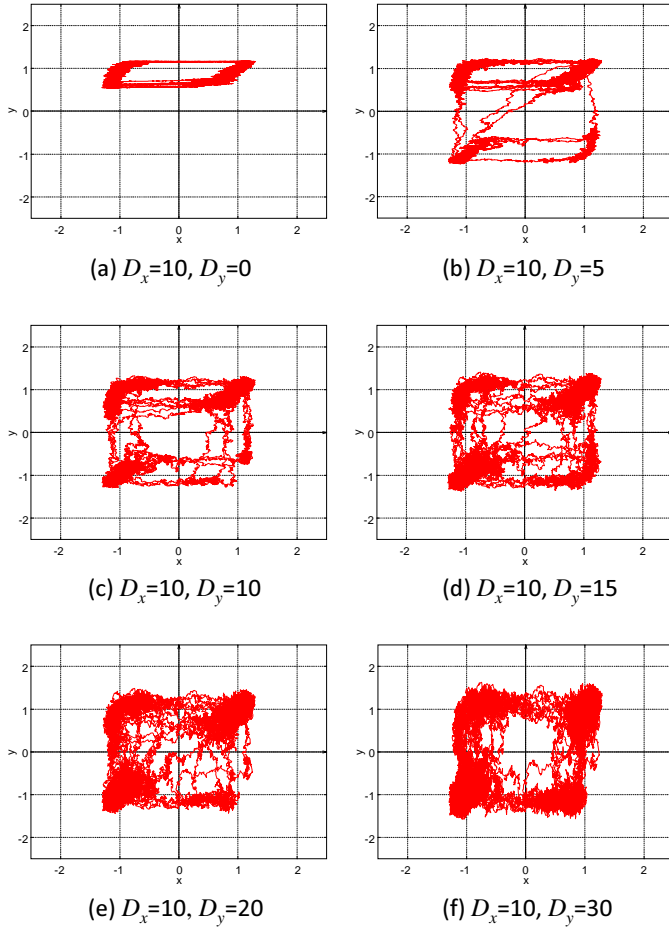


Fig. 4. Output of SR in four-stable state (fixed D_x , variable D_y).

we can observe that the point (x, y) frequently hops in x -axis since the noise level of x (D_x) is stronger than that of y (D_y). Third, in the case of $D_y = 10$ (Fig. 4(c)), the point (x, y) symmetrically hops in (x, y) plane because D_x and D_y are same values. Fourth, in the case of $D_y = 15$ (Fig. 4(d)) and $D_y = 20$ (Fig. 4(e)), we can find that the number of the point's move increases. In other words, the point (x, y) actively hops in (x, y) plane. Finally, in the case of $D_y = 30$ (Fig. 4(f)), the point's move around the origin is not confirmed in (x, y) plane. Here, we compare the results of the same noise level ($D_x = D_y$) and the different noise level (fixed D_x , variable D_y). By setting the different noise level, we can make the difference point's between x -axis and y -axis and can confirm that the point move linearly. Therefore, to use the different noise levels is effective for controlling the state of the SR in the quadruple-well potential.

V. CONCLUSIONS

In this paper, we have analyzed SR in the quadruple-well potential which extended the SR in a double-well potential. As results of computer simulations, it have been confirmed that the various point's moves by changing noise levels. However, we have performed only the qualitative analysis, such as the

behavior of the point (x, y) , in this study. Therefore, the quantitative analysis of the SR in the quadruple-well potential, such as a signal-to-noise ratio (SNR), is our future work.

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